

We start with the following linear model:

$$Y_{jt} = \beta_0 + \beta_1 X_{jt}^1 + \dots + \beta_N X_{jt}^N + a_j + \mu_{jt} \quad [S1.1]$$

$$t=2008, 2011 \ ; \ j=firm \ 1, \dots, firm \ N$$

The variable a_j represents the “unobserved heterogeneity” and covers the unobserved factors that do not change over time, but which affect the endogenous variable. Generally, the variable a_j , is also known as the “unobserved effect” or “fixed effect”. Hence, the model (S1.1) takes the names of the unobserved effects model or fixed effects model. The idiosyncratic error, μ_{jt} , represents the unobserved factors that change over time and which affect the endogenous variable. The combination of the two terms, $(a_j + \mu_{jt})$, is known as the composite error.

Given that a_j does not depend on time, we can take the first differences of the data from the two years. For a cross-sectional observation j , we can estimate for each year:

$$Y_{j2011} = (\beta_0 + \delta_0) + \beta_1 X_{j2011}^1 + \dots + \beta_N X_{j2011}^N + a_j + \mu_{j2011} \quad [S1.2]$$

$$Y_{j2008} = \beta_0 + \beta_1 X_{j2008}^1 + \dots + \beta_N X_{j2008}^N + a_j + \mu_{j2008} \quad [S1.3]$$

$$j=firm \ 1, \dots, firm \ N$$

If we take away equations [I.2] y [I.3], we are left with:

$$(Y_{j2011} - Y_{j2008}) = \delta_0 + \beta_1 (X_{j2011}^1 - X_{j2008}^1) + \dots$$

$$\dots + \beta_N (X_{j2011}^N - X_{j2008}^N) + (\mu_{j2011} - \mu_{j2008}) \quad [S1.4]$$

The final expression of the first differences model is:

$$\Delta Y_j = \delta_0 + \beta_1 \Delta X_j^1 + \dots + \beta_N \Delta X_j^N + \Delta \mu_j \quad [S1.5]$$

where “ Δ ” represents the change from $t=2008$ to $t=2011$. The unobserved effect, a_j , does not appear in the equation [S1.5], as it has been eliminated by using the difference. The intercept that appears in the new model, δ_0 , is in reality the change in the constant from $t=2008$ to $t=2011$.

Figure S1. Development of the first differences model